

Parts 2-4: Regular Variation, Extreme Value Theory, Hidden Regular Variation, Conditioned Limit Laws

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1. Regularly varying functions and measures

A function $U : \mathbb{R}_+^d \mapsto \mathbb{R}_+$ is multivariate regularly varying if

$$\lim_{t \rightarrow \infty} \frac{U(t\mathbf{x})}{U(t\mathbf{1})} = \lambda(\mathbf{x}) \neq 0,$$

for $\mathbf{x} \geq \mathbf{0}$, $\mathbf{x} \neq \mathbf{0}$. If $d = 1$, limit must be a power function and we are dealing with functions U which are asymptotically like power functions; for $d = 1$,

$$\frac{U(tx)}{U(t)} \rightarrow x^\rho, \quad \rho \in \mathbb{R}.$$

Call ρ the **index** and when $d = 1$ we write $U \in RV_\rho$.

When $d > 1$, a scaling argument shows $\exists \rho \in \mathbb{R}$ and

$$\lambda(t\mathbf{x}) = t^\rho \lambda(\mathbf{x}),$$

and $U(t\mathbf{1}) \in RV_\rho$. Therefore, equivalent formulation is there exists $V \in RV_\rho$ such that

$$\frac{U(t\mathbf{x})}{V(t)} \rightarrow \lambda(\mathbf{x}) \neq 0,$$

or (sequential version when $\rho > 0$) $\exists b_n \rightarrow \infty$ such that

$$\frac{U(b_n \mathbf{x})}{n} \rightarrow \lambda(\mathbf{x}).$$

(Then if $V \uparrow$ can set $b_n = V^{\leftarrow}(n)$.)

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1.1. Connection to domain of attraction characterizations.

Suppose $\{X_n, n \geq 1\}$ are iid non-negative, common distribution function $F(x)$. The extreme is

$$M_n = \bigvee_{i=1}^n X_i = \max\{X_1, \dots, X_n\}.$$

One of the extreme value distributions is the Fréchet:

$$\Phi_\alpha(x) := \exp\{-x^{-\alpha}\}, \quad x > 0, \alpha > 0.$$

Questions:

- What are conditions on F , called *domain of attraction conditions*, so that there exists $b_n > 0$ such that

$$P[b_n^{-1}M_n \leq x] = F^n(b_n x) \rightarrow \Phi_\alpha(x). \quad (1)$$

When (1) holds, we say F is in the domain of attraction of Φ_α and write $F \in MDA(\Phi_\alpha)$.

- How do you characterize the normalization sequence $\{b_n\}$?

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Answers:

- DofA: One argues that we must have

$$x_0 = \sup\{x : F(x) < 1\} = \infty,$$

and Furthermore

$$b_n \rightarrow \infty.$$

In (1), take logarithms to get for

$$\lim_{n \rightarrow \infty} n(-\log F(b_n x)) = x^{-\alpha}, \quad x > 0.$$

Use

$$-\log(1 - z) \sim z, \quad (z \rightarrow 0,$$

and (1) is equivalent to

$$\lim_{n \rightarrow \infty} n(1 - F(b_n x)) = x^{-\alpha}, \quad x > 0. \quad (2)$$

This is the sequential version of regular variation for $\bar{F} = 1 - F$.

- Characterize b_n : Set $U(x) = 1/(1 - F(x))$ and (2) is the same as

$$U(b_n x)/n \rightarrow x^\alpha, \quad x > 0,$$

and inverting, we find that

$$\frac{U^-(ny)}{b_n} \rightarrow y^{1/\alpha}, \quad y > 0. \quad (3)$$

So $U^{\leftarrow}(n) = (1/(1-F))^{\leftarrow}(n) \sim b_n$ and this determines b_n by the convergence to types theorem.

1.2. Conclusion: Connecting regular variation and domains of attraction in one dimension.

With

$$\Phi_{\alpha}(x) = \exp\{-x^{-\alpha}\}, \quad x > 0, \alpha > 0,$$

we have

$$F \in MDA(\Phi_{\alpha}) \text{ iff } \lim_{t \rightarrow \infty} \frac{\bar{F}(tx)}{\bar{F}(t)} = x^{-\alpha}, \quad x > 0;$$

that is, $\bar{F} \in RV_{-\alpha}$.

1.3. Behavior of one dimensional regularly varying functions:

Regularly varying functions behave asymptotically like power functions. Helpful notation: Call $L(x)$ slowly varying if $L(\cdot) \in RV_0$. Then if

$$U \in RV_{\rho}$$

we have

$$L(x) := U(x)/x^{\rho} \in RV_0$$

and we can write

$$U(x) = x^{\rho} L(x).$$

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Rules for manipulating:

- Karamata theorem: For $\rho > -1$,

$$\int_0^x U(t) dt$$

behaves as if $L(t)$ comes out of the integral and the power part integrates. So if $U(x) = x^\rho L(x)$, then

$$\begin{aligned} \int_0^x U(t) dt &= \int_0^x t^\rho L(t) dt \\ &\sim L(x) \int_0^x t^\rho dt = L(x) \frac{x^{\rho+1}}{\rho+1} \\ &= \frac{xU(x)}{\rho+1}. \end{aligned}$$

- Differentiation: If $U \in RV_\rho$ has a monotone density $u(x)$, then $u(x) \in RV_{\rho-1}$ (as if it were a power function).

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- Regularly varying functions have smooth asymptotically equivalent versions which comes from the *Karamata representation*: if $U \in RV_\rho$,

$$U(x) = c(x) \exp\left\{\int_1^x \frac{\rho(s)}{s} ds\right\},$$

where

$$c(x) \rightarrow c_0, \quad \rho(t) \rightarrow \rho.$$

- The regular variation ratio converges locally uniformly.

1.4. Multivariate Regular Variation for Multivariate Distribution Functions and Measures

Application to distributions: Let \mathbf{Z} be a random vector in \mathbb{R}_+^d with df F . A *regularly varying tail* means

$$\frac{1 - F(t\mathbf{x})}{1 - F(t\mathbf{1})} \rightarrow \nu_*([\mathbf{0}, \mathbf{x}]^c),$$

for some Radon measure ν_* . Awkward to deal with multivariate df's and better to deal with measures.

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Let

$$\begin{aligned}\mathbb{E} &= [0, \infty]^d \setminus \{\mathbf{0}\} \\ \mathfrak{N} &= \{\mathbf{x} \in \mathbb{E} : \|\mathbf{x}\| = 1\}, \\ R &= \|\mathbf{Z}\|, \quad \Theta = \frac{\mathbf{Z}}{\|\mathbf{Z}\|} \in \mathfrak{N}.\end{aligned}$$

The following are equivalent.

1. \exists a Radon measure ν_* on \mathbb{E} such that

$$\begin{aligned}\lim_{t \rightarrow \infty} \frac{1 - F(t\mathbf{x})}{1 - F(t\mathbf{1})} &= \lim_{t \rightarrow \infty} \frac{\mathbb{P}\left[\frac{\mathbf{Z}_1}{t} \in [\mathbf{0}, \mathbf{x}]^c\right]}{\mathbb{P}\left[\frac{\mathbf{Z}_1}{t} \in [\mathbf{0}, \mathbf{1}]^c\right]} \\ &= c\nu_*([\mathbf{0}, \mathbf{x}]^c),\end{aligned}$$

some $c > 0$ and for all points $\mathbf{x} \in [\mathbf{0}, \infty) \setminus \{\mathbf{0}\}$ which are continuity points of $\nu_*([\mathbf{0}, \cdot]^c)$.

2. \exists a function $b(t) \rightarrow \infty$ and a Radon measure ν_* on \mathbb{E} such that in $M_+(\mathbb{E})$

$$t\mathbb{P}\left[\frac{\mathbf{Z}}{b(t)} \in \cdot\right] \xrightarrow{v} \nu_*, \quad t \rightarrow \infty.$$

3. \exists a pm $S(\cdot)$ on \mathfrak{N} and $b(t) \rightarrow \infty$ such that

$$t\mathbb{P}\left[\left(\frac{R}{b(t)}, \Theta\right) \in \cdot\right] \xrightarrow{v} c\nu_\alpha \times S$$

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in $M_+((0, \infty] \times \mathbb{N})$, where $c > 0$.

Notes:

- Can replace function $b(t)$ by sequence $b(n)$.
- \xrightarrow{v} means vague convergence defined as follows: Let $M_+(\mathbb{E})$ be the Radon measures on \mathbb{E} . (Radon means the measure is finite on relatively compact sets.) $M_+(\mathbb{E})$ can be metrized by vague convergence: Let $\mu_n(\cdot), n \geq 0$ be measures in $M_+(\mathbb{E})$. Then

$$\mu_n \xrightarrow{v} \mu_0$$

iff

$$\mu_n(f) := \int_E f d\mu_n \rightarrow \int_E f d\mu =: \mu(f) \quad (n \rightarrow \infty)$$

for all non-negative, continuous functions with compact support on \mathbb{E} .

- Generally, vague convergence can be reduced to convergence of measures on a class of rectangles suited to the compact sets of \mathbb{E} .

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1.5. Statistical difficulty.

- This formulation is good for theory but bad for applications.
- Being able to norm each component by the same $b(t)$ means marginal tails are the same—almost never happens in practice. Multivariate data from a distribution with heavy tailed marginals, never have the same α 's.

Set

$$\mathbf{Z} = (Z^{(1)}, \dots, Z^{(d)}).$$

Norming each component with the same $b(t)$ means

$$\mathbb{P}[Z^{(i)} > x] \sim c_{ij} \mathbb{P}[Z^{(j)} > x], \quad x \rightarrow \infty.$$

and if $c_{ij} > 0$, then the tail index of $Z^{(i)}$ and $Z^{(j)}$ are the same.

Examples:

- Xchr vs USD of (FR, JAP).
- (Size of document downloaded, download time).
- (log return IBM, log return P&G).

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1.5.1. More flexibility.

A more flexible defn of a multivariate heavy tail is: $\exists b_n^{(i)} \rightarrow \infty$ for $i = 1, \dots, d$ and \exists Radon ν such that

$$n\mathbb{P}\left[\left(\frac{Z^{(i)}}{b_n^{(i)}}, i = 1, \dots, d\right) \in \cdot\right] \rightarrow \nu. \quad (4)$$

THEOREM. If (4) and

$$n\mathbb{P}\left[\frac{Z^{(i)}}{b_n^{(i)}} \in \cdot\right] \rightarrow \nu_{\alpha_i}, \quad \nu_{\alpha_i}(x, \infty] = x^{-\alpha_i}, \quad x > 0, \alpha_i > 0, \forall i,$$

then

$$nF_*(n\cdot) = n\mathbb{P}\left[\left(\frac{1}{\frac{1-F_{(i)}(Z^{(i)})}{n}}, i = 1, \dots, d\right) \in \cdot\right] \rightarrow \nu_*(\cdot)$$

where ν_* is *standard*; that is, Radon and

$$\nu_*(tA) = t^{-1}\nu_*(A).$$

Note if for $i = 1, \dots, d$

$$1 - F_{(i)}(x) \sim x^{-\alpha_i}, \quad x \rightarrow \infty,$$

then

$$n\mathbb{P}\left[\left(\frac{(Z^{(i)})^{\alpha_i}}{n}, i = 1, \dots, d\right) \in \cdot\right] \rightarrow \nu_*(\cdot).$$

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1.5.2. How to get the standard case in practice:

(a) Simple minded. Hope (assume, pray) $1 - F_{(i)}(x) \sim x^{-\alpha_i}$ for all i and then power up. (Slow variation hard (impossible?) to detect in practice and this works reasonably.)

BUT: Must estimate α 's. (Ouch!)

(b) Use ranks method.

BUT: Lose independence among observations.

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1.6. Significance of the limit measure.

The limit measure ν_* controls the (asymptotic) dependence structure.

1.6.1. Asymptotic independence.

The distribution F of \mathbf{Z} possesses the property of *asymptotic independence* if

1. $\nu_*((\mathbf{0}, \infty)) = 0$ so that ν_* concentrates on the axes;
OR
2. S concentrates on $\{\mathbf{e}_i, i = 1, \dots, d\}$.

For $d = 2$ this means

$$\begin{aligned} \mathbb{P}[Z^{(2)} > t | Z^{(1)} > t] &= \frac{\mathbb{P}[Z^{(2)} > t, Z^{(1)} > t]}{\mathbb{P}[Z^{(1)} > t]} \\ &\rightarrow (\text{const}) \nu_*\left(\mathbf{1}, \infty\right] = 0. \end{aligned}$$

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Remarks:

- The probability of both components being large is negligible.
- The concept was invented to answer the following query: Let $\{\mathbf{Z}_j, j \geq 1\}$ be iid, non-negative random vectors in \mathbb{R}_+^d with common distribution F . The necessary and sufficient condition for there to exist $b(n) \rightarrow \infty$ such that

$$P\left[\bigvee_{i=1}^n \frac{Z_i^{(l)}}{b(n)} \leq x^{(l)}, l = 1, \dots, d\right] \rightarrow G(\mathbf{x})$$

is $1 - F$ is multivariate regularly varying with the original definition. The necessary and sufficient condition for G to be a product distribution is asymptotic independence.

1.6.2. Asymptotic dependence.

The distribution F of \mathbf{Z}_1 possesses the property of *asymptotic dependence* if

1. ν_* concentrates on $\{t \frac{\mathbf{1}}{\|\mathbf{1}\|} : t > 0\}$, the diagonal line,
or
2. S concentrates on $\{\frac{\mathbf{1}}{\|\mathbf{1}\|}\}$.

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Means:

- $$\mathbb{P}[Z^{(2)} > t | Z^{(1)} > t] \rightarrow 1.$$

- $$G(\mathbf{x}) = G(\bigwedge_{i=1}^d x^{(i)}),$$

the distribution of a random vector all of whose components are equal.

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1.7. Formulate the domain of attraction problem in Multivariate EVT

By analogy with the one dimensional problem discussed in relation to regular variation, we consider the following problem(s): Given $\mathbf{X}_1, \dots, \mathbf{X}_n$ iid random vectors in \mathbb{R}^d with common distribution F .

1.7.1. Problems:

- When do there exist

$$\mathbf{a}(n) = (a^{(1)}(n), \dots, a^{(d)}(n)) \in \mathbb{R}_+^d, \quad \mathbf{b}(n) = (b^{(1)}(n), \dots, b^{(d)}(n)) \in \mathbb{R}^d,$$

and a probability distribution G such that

$$\begin{aligned} P\left[\left(\bigvee_{j=1}^n \mathbf{X}_j - \mathbf{b}(n)\right) / \mathbf{a}(n) \leq \mathbf{x}\right] &= F^n(\mathbf{a}(n)\mathbf{x} + \mathbf{b}(n)) \\ &= P\left[\left(\bigvee_{j=1}^n X_j^{(i)} - b^{(i)}(n)\right) / a^{(i)}(n) \leq x^{(i)}; i = 1, \dots, d\right] \rightarrow G(\mathbf{x})? \end{aligned} \tag{5}$$

- What is the family of possible limits G ?
- For a given G how do you characterize $\mathbf{a}(n)$ and $\mathbf{b}(n)$?

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- For a given G in the family of possible limits, what properties does F have to satisfy in order for (5) to hold.

If (5) holds, we say F is in the domain of attraction of G and write $F \in MDA(G)$.

1.7.2. Some superficial and cheap answers:

- Joint convergence implies marginal convergence:

$$F_i^n(a^{(i)}(n)x^{(i)} + b^{(i)}(n)) \rightarrow G_i(x^{(i)}), \quad (n \rightarrow \infty).$$

So if we know how to find normalizing constants in one dimension, we can find them in d-dimensions.

- From (5), we take logarithms to get

$$n(1 - F(\mathbf{a}(n)\mathbf{x} + \mathbf{b}(n))) \rightarrow -\log G(\mathbf{x}), \quad (G(\mathbf{x}) > 0).$$

Re-write this as

$$nP\left\{\left[\frac{\mathbf{X}_1 - \mathbf{b}(n)}{\mathbf{a}(n)} \leq \mathbf{x}\right]^c\right\} \rightarrow -\log G(\mathbf{x}),$$

or

$$nP\left[\frac{\mathbf{X}_1 - \mathbf{b}(n)}{\mathbf{a}(n)} \in \cdot\right] \xrightarrow{v} \nu(\cdot),$$

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where

$$\nu([-\infty, \mathbf{x}]^c) = -\log G(\mathbf{x}).$$

The measure ν is called the *exponent measure* of G or the *limit measure*, since

$$G(\mathbf{x}) = \exp\{-\nu([-\infty, \mathbf{x}]^c)\}.$$

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2. Regular variation on cones

Suppose CONE is a cone centered at $\mathbf{0}$:

$$\mathbf{x} \in \text{CONE} \quad \Rightarrow \quad t\mathbf{x} \in \text{CONE}, \quad t > 0.$$

Suppose \mathbf{Z}^* is a random vector. \mathbf{Z}^* has a regularly varying distribution **in standard form** on CONE if

$$tP\left[\frac{\mathbf{Z}^*}{t} \in \cdot\right] \xrightarrow{v} \nu^*(\cdot), \quad \text{in } M_+(\text{CONE}).$$

Cone CONE	Application
$\mathbb{E} = [\mathbf{0}, \infty] \setminus \{\mathbf{0}\}$	multivariate extreme value theory
$\mathbb{E}_0 = (\mathbf{0}, \infty]$	hidden regular variation, coefficient of tail dependence;
$\mathbb{E}_{\sqcap} = [0, \infty] \times (0, \infty]$	Conditioned limit theorems when one component is extreme.
$[-\infty, \infty] \setminus \{\mathbf{0}\}$	weak conv to stable laws

Table 1: Theories stemming from standard multivariate regular variation on different cones.

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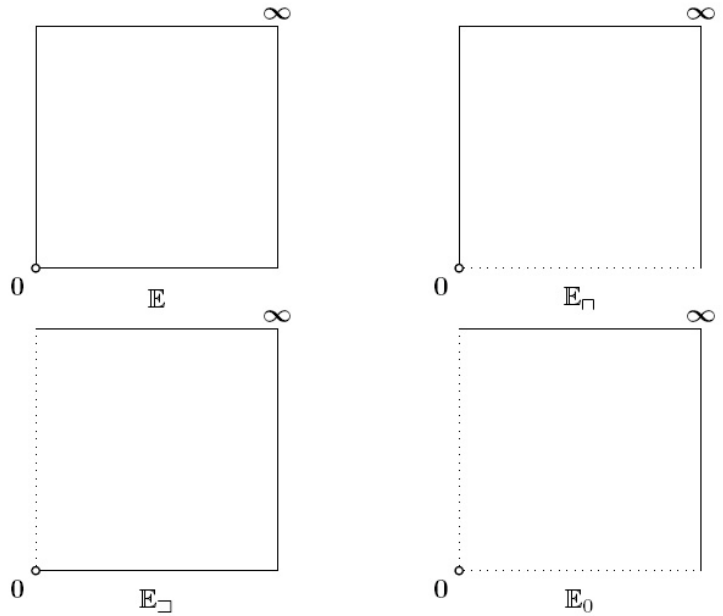


FIGURE 1. The different cones in 2-dimensions

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2.1. The cone $\mathbb{E} = [0, \infty) \setminus \{0\}$ and EVT.

Let $\mathbf{Z}^* = (Z^{*(1)}, \dots, Z^{*(d)})$ be standard regularly varying random vector on \mathbb{E} :

$$tP\left[\frac{\mathbf{Z}^*}{t} \in \cdot\right] \xrightarrow{v} \nu^*(\cdot).$$

Suppose $(b^{(i)}, a^{(i)})$, $i = 1 \dots d$ satisfy

$$\frac{b^{(i)}(tx) - b^{(i)}(t)}{a^{(i)}(t)} \rightarrow \psi_i(x) \neq 0, \quad x > 0, t \rightarrow \infty, \quad (6)$$

and that each $b^{(i)}$ is non-decreasing. In inverted form (6) is

$$b^{(i)\leftarrow}(a^{(i)}(t)z + b^{(i)}(t))/t \rightarrow \psi_i^{\leftarrow}(z), \quad t \rightarrow \infty. \quad (7)$$

Then based on standard regular variation

$$\begin{aligned} & tP\left\{\left[\frac{b^{(i)}(Z^{*(i)}) - b^{(i)}(t)}{a^{(i)}(t)} \leq x^{(i)}, i = 1 \dots d\right]^c\right\} \\ &= tP\left\{\left[\frac{Z^{*(i)}}{t} \leq b^{(i)\leftarrow}(a^{(i)}(t)x^{(i)} + b^{(i)}(t))/t, i = 1 \dots d\right]^c\right\} \\ &\rightarrow \nu_*\left(\{\mathbf{y} : y^{(i)} \leq \psi_i^{\leftarrow}(x^{(i)}), i = 1 \dots d\}^c\right). \end{aligned} \quad (8)$$

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Conclusions:

- Given \mathbf{Z}^* which is standard regularly varying on \mathbb{E} with limit measure ν^* , we have

$$\mathbf{X} = (b^{(i)}(Z^{*(i)}), i = 1, \dots, d)$$

in the multivariate domain of attraction of an EV distribution G with exponent measure

$$\nu^* (\{\mathbf{y} : y^{(i)} \leq \psi_i^{\leftarrow}(x^{(i)}), i = 1 \dots d\}^c).$$

- Vice versa: Given a random vector \mathbf{X} in the domain of attraction of the multivariate EV distribution $G(\mathbf{x})$, there exist monotone transformations $b^{(i)}(t)$, $i = 1, \dots, d$ such that

$$\mathbf{Z}^* = ((b^{(i)})^{\leftarrow}(X^{(i)}), i = 1, \dots, d)$$

is standard regularly varying.

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Where do $b^{(i)}$ and $a^{(i)}$ come from?

The equations (6) and (7) are the one-dimensional domain of attraction conditions and say

$$F_i(x) := P[X^{(i)} \leq x] \in MDA(G_{\gamma_i}), \quad \gamma_i \in \mathbb{R} \quad i = 1, \dots, d$$

with

$$b^{(i)}(t) = \left(\frac{1}{1 - F_i} \right)^{\leftarrow}(t), \quad i = 1, \dots, d$$

and are equivalent to

$$t(1 - F_i(a^{(i)}(t)x + b^{(i)}(t))) \rightarrow -\log G_{\gamma_i}(x) \quad i = 1, \dots, d.$$

and comparing with (7) we see

$$\psi_i^{\leftarrow}(z) = \frac{1}{-\log G_{\gamma_i}(z)}.$$

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3. Standardization

Standardization is the process of marginally transforming

$$\mathbf{X} \mapsto \mathbf{Z}^*$$

so that the distribution of \mathbf{Z}^* is standard regularly varying on a cone \mathbf{CONE} : For some Radon measure $\nu^*(\cdot)$

$$tP\left[\frac{\mathbf{Z}^*}{t} \in \cdot\right] \xrightarrow{v} \nu^*(\cdot), \quad \text{in } M_+(\mathbf{CONE}).$$

For EVT,

$$\mathbf{CONE} = \mathbb{E} = [\mathbf{0}, \infty] \setminus \{\mathbf{0}\}.$$

In general, depending on the cone, this says one or more components of \mathbf{Z}^* are asymptotically Pareto. For the EVT case, each is asymptotically Pareto.

3.1. Theoretical advantages of standardization:

- Standardization is analogous to the copula transformation but is better suited to studying limit relations (Klüppelberg and Resnick, 2008).

- In Cartesian coordinates, the limit measure has scaling property:

$$\nu^*(c \cdot) = c^{-1} \nu^*(\cdot), \quad c > 0.$$

- The scaling in Cartesian coordinates allows transformation to polar coordinates to yield a product measure: An angular measure exists allowing characterization of limits:

$$\nu^* \left\{ \mathbf{x} : \|\mathbf{x}\| > r, \frac{\mathbf{x}}{\|\mathbf{x}\|} \in \Lambda \right\} = r^{-1} S(\Lambda),$$

for Borel subsets Λ of the unit sphere in CONE .

- For EVT, S is a finite measure (wlog taken to be a pm) but when $\text{CONE} = \mathbb{E}_0$ or $\text{CONE} = \mathbb{E}_\square$, S is NOT necessarily finite.
- See de Haan and Resnick (1977), Resnick (1987), Mikosch (2005, 2006), de Haan and Ferreira (2006), Resnick (2007).

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4. Reduction of multivariate regular variation to a one-dimensional criterion.

For a general cone CONE , one can hope to dream up variants of the Cramer-Wold device to reduce multivariate regular variation to one dimensional regular variation.

Example: EVT

For EVT, $\text{CONE} = \mathbb{E} = [0, \infty] \setminus \{0\}$. Then

$$tP\left[\frac{\mathbf{Z}^*}{t} \in \cdot\right] \xrightarrow{v} \nu^*(\cdot), \quad \text{in } M_+(\mathbb{E})$$

iff

$$\forall \mathbf{s} \geq 0, \mathbf{s} \neq 0,$$

$$\lim_{t \rightarrow \infty} tP\left[\bigvee_{i=1}^d s^{(i)} Z^{*(i)} > tx\right] = c(\mathbf{s})x^{-1}, \quad x > 0.$$

See [de Haan \(1978\)](#).

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5. Asymptotic Independence in EVT

If (X, Y) is in a bivariate domain of attraction of a multivariate extreme value distribution $G(x, y)$,

$$tP\left\{\left[\frac{X - \beta(t)}{\alpha(t)} \leq x, \frac{Y - b(t)}{a(t)} \leq y\right]^c\right\} \rightarrow -\log G(x, y), \quad t \rightarrow \infty,$$

then *asymptotic independence* of (X, Y) means

$$tP\left[\frac{X - \beta(t)}{\alpha(t)} > x, \frac{Y - b(t)}{a(t)} > y\right] \rightarrow 0, \quad t \rightarrow \infty.$$

This roughly says, (de Haan and Ferreira, 2006, Resnick, 1987)

- The probability of both X and Y being biggish is smallish.
- Componentwise maxima (normalized) of iid samples of (X, Y) are asymptotically distributed as a product measure.

If $\mathbf{Z}^* \in \mathbb{R}_+^d$ has a standard regularly varying distribution, then asymptotic independence means

$$tP\left[\frac{\mathbf{Z}^*}{t} \in \cdot\right] \xrightarrow{v} \nu^*(\cdot)$$

where

$$\nu^*\{\mathbf{x} \in \mathbb{E} : x^{(i)} \wedge x^{(j)} > 0, \text{ some } i, j\} = 0.$$

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6. Examples

6.1. Asymptotic independence but no hidden regular variation

Let $U \sim U(0, 1)$ and

$$(X, Y) = \left(\frac{1}{U}, \frac{1}{1-U} \right).$$

Then (X, Y) has a standard regularly varying distribution which possesses asymptotic independence.

Reduction to 1-dimensional criterion:

$$P[X \vee Y > x] = \frac{2}{x}, \quad x > 2.$$

Note: we have not checked ALL max-linear combinations BUT

- this is representative calculation,
- This suggests what is likely to be checked in practice.

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6.2. Example: Same rv's; different variation on different cones.

Let X and Z be iid Pareto(1) random variables and define

$$Y = X^2 \wedge Z^2.$$

Then in \mathbb{E}, \mathbb{E}_0 and \mathbb{E}_\square check convergence on representative relatively compact sets:

- In $M_+(\mathbb{E})$, asymptotic independence,

$$t\mathbb{P}\left[\left(\frac{X}{t}, \frac{Y}{t}\right) \in ([0, x] \times [0, y])^c\right] \rightarrow \frac{1}{x} + \frac{1}{y}, \quad x \vee y > 0.$$

- In $M_+(\mathbb{E}_0)$:

$$t\mathbb{P}\left[\left(\frac{X}{t^{2/3}}, \frac{Y}{t^{2/3}}\right) \in (x, \infty] \times (y, \infty]\right] \rightarrow \frac{1}{x\sqrt{y}}, \quad x \wedge y > 0,$$

or in standard form,

$$t\mathbb{P}\left[\left(\frac{X^{3/2}}{t}, \frac{Y^{3/2}}{t}\right) \in (x, \infty] \times (y, \infty]\right] \rightarrow \frac{1}{x^{2/3}y^{1/3}}, \quad x \wedge y > 0.$$

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- In $M_+(\mathbb{E}_\square)$:

$$t\mathbb{P}\left[\left(\frac{X}{t^{1/2}}, \frac{Y}{t}\right) \in [0, x] \times (y, \infty]\right] \rightarrow \frac{1}{y} - \frac{1}{\sqrt{y}} \times \frac{1}{x \vee \sqrt{y}}, \quad x \geq 0, y > 0,$$

or in standard form,

$$t\mathbb{P}\left[\left(\frac{X^2}{t}, \frac{Y}{t}\right) \in [0, x] \times (y, \infty]\right] \rightarrow \frac{1}{y} - \frac{1}{\sqrt{y}} \times \frac{1}{\sqrt{x} \vee \sqrt{y}}, \quad x \geq 0, y > 0.$$

Angular measures

For these examples we get the angular measure after polar co-ordinate transformation

$$(x, y) \mapsto (r, \theta) := \left(x + y, \frac{x}{x + y}\right).$$

- On \mathbb{E} ,

$$S(d\theta) = \frac{1}{2}[\delta_{\{0\}}(d\theta) + \delta_{\{1\}}(d\theta)].$$

- For the standard form on \mathbb{E}_0 we have the angular measure

$$S(d\theta) = \frac{1}{\theta^{5/3}(1-\theta)^{4/3}}d\theta, \quad 0 < \theta < 1.$$

The density is not integrable near 0 or 1 so S is not a finite measure on $(0, 1)$.

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- For the standard form on \mathbb{E}_\square

$$S(d\theta) = \begin{cases} \theta^{-\frac{3}{2}}(1-\theta)^{-\frac{3}{2}}d\theta, & \frac{1}{2} \leq \theta < 1 \\ 0 & 0 \leq \theta < \frac{1}{2}. \end{cases}$$

This is not integrable near 1 so S is not finite on $[0, 1)$.

6.3. Angular measure finite or infinite?

Example of class of examples of standard regular variation on \mathbb{E}_\square indexed by distributions on $[0, \infty]$. Suppose

$$R \sim \text{Pareto}(1) \text{ on } [1, \infty), \quad \theta \geq 0, \theta \sim G(\cdot) \text{ on } [0, \infty].$$

Assume $R \perp \theta$. Define

$$(X, Y) = (R\theta, R).$$

Therefore we have for $y > 0, x \geq 0$ (and $ty > 1$),

$$\begin{aligned} t\mathbb{P}\left(\frac{X}{t} \leq x, \frac{Y}{t} > y\right) &= t\mathbb{P}\left(\frac{R\theta}{t} \leq x, \frac{R}{t} > y\right) = t \int_{ty}^{\infty} \mathbb{P}\left(\theta \leq \frac{tx}{r}\right) r^{-2} dr \\ &= \frac{1}{x} \int_0^{x/y} G(s) ds = \mu([0, x] \times (y, \infty)). \end{aligned}$$

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Polar co-ordinates: The the angular measure $S(\cdot)$ on \mathbb{E}_\square for $0 \leq \eta < 1$ is given by

$$S([0, \eta]) = \mu\{(u, v) : u + v > 1, \frac{y}{u+v} \leq \theta\}.$$

Hence

$$\begin{aligned} tP\left[\frac{X+Y}{t} > 1, \frac{X}{X+Y} \leq \eta\right] &= tP\left[\frac{R\theta + R}{t} > 1, \frac{R\theta}{R\theta + R} \leq \eta\right] \\ &= tP\left[\frac{R(1+\theta)}{t} > 1, \theta \leq \frac{\eta}{1-\eta}\right] \\ &= t \int_{0 \leq s \leq \frac{\eta}{1-\eta}} P\left[\frac{R}{t}(1+s) > 1\right] G(ds) \\ &\rightarrow \int_{0 \leq s \leq \frac{\eta}{1-\eta}} (1+s)G(ds) =: S[0, \eta]. \end{aligned}$$

Hence

$$S([0, \eta]) = \int_{0 \leq s \leq \frac{\eta}{1-\eta}} (1+s)G(ds), \quad 0 \leq \eta < 1.$$

Conclude: S is a finite angular measure on $[0, 1)$ if and only if G has first moment.

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7. How to Standardize?

Theoretical formulations often assume the *standard case*.

- Standard case almost never happens in practice.
- A vector which is standard regularly varying has each component having the same (asymptotically equivalent) tail.

How to transform to the standard case in practice?

- In heavy tail analysis, the simplest method: Hope $1 - F_{(i)}(x) \sim x^{-\alpha_i}$ for all i and then power up.
BUT: Must estimate α 's.
- More generally, for EVT: estimate marginals (somehow) and transform using the marginals.
BUT: Difficult to quantify the error made when estimating marginal distributions.
- Use ranks method (Huang, 1992; de Haan & de Ronde).
BUT: Lose independence among observations.

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The ranks method:

Given d -dimensional random vectors $\{\mathbf{X}_1, \dots, \mathbf{X}_n\}$ where

$$\mathbf{X}_i = (X_i^{(1)}, \dots, X_i^{(d)}), \quad i = 1, \dots, n,$$

define the (anti)-ranks for each component: Comparing the j th components, $X_1^{(j)}, \dots, X_n^{(j)}$, the anti-rank of $X_i^{(j)}$ is

$$\begin{aligned} r_i^{(j)} &= \sum_{l=1}^n 1_{[X_l^{(j)} \geq X_i^{(j)}]} \\ &= \# \text{ jth components } \geq X_i^{(j)}. \end{aligned}$$

Replace each \mathbf{X}_i by

$$\mathbf{X}_i \mapsto (1/r_i^{(j)}, j = 1, \dots, d) =: \mathbf{Z}^*.$$

Allows

- Estimation of the angular measure S .
- Estimation of the hidden angular measure in hidden regular variation (Heffernan and Resnick, 2005).

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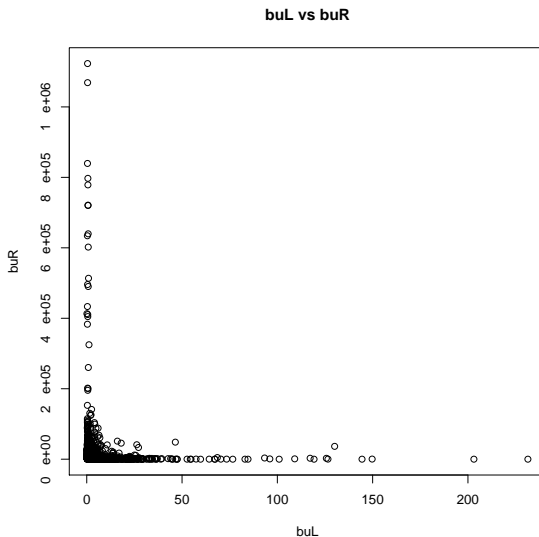
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8. Data examples

8.1. BuL vs BuR Scatterplot:

Data processed from the original 1995 Boston University data; 4161 file sizes (F) and download times (L) noted and transmission rates (R) inferred. The data consists of bivariate pairs (R,L).

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8.2. UNC

Steps:

- Transform (F,R) data using rank method.
- Convert to polar coordinates.
- Keep 2000 pairs with biggest radius vector.
- Compute density estimate for angular measure S .

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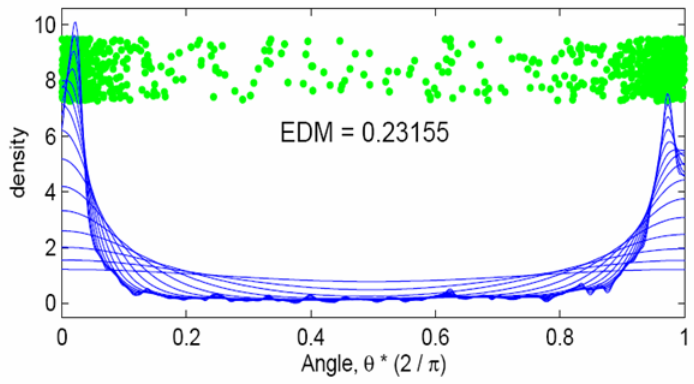
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8.3. The Auckland-II trace

(<http://pma.nlanr.net/traces/long/auck2.html>) a collection of long GPS-synchronized IP header traces captured at the University of Auckland Internet uplink since 1999.

- Connection level data characterized by packet headers.
- connection = 5 tuple (source ip, dest ip, source port, dest port, protocol)
- Amalgamate the data into clusters in hopes that cluster heads are approx Poisson.
 - No unique way to do this.
 - One proposal:
 - * Organize packets into e2e streams—packets with same ip source and destination. Con: ignores application.
 - * Create sessions by clustering e2e streams according to the rule that 2 consecutive packets part of the same cluster if time separation between them is below a threshold.
 - * For a session, compute total payload (F), duration (L) and then (average) rate (R)
 - * Compute a peak rate for each session by chopping session durations into small bins, computing the average rate per bin, and taking max of these rates.

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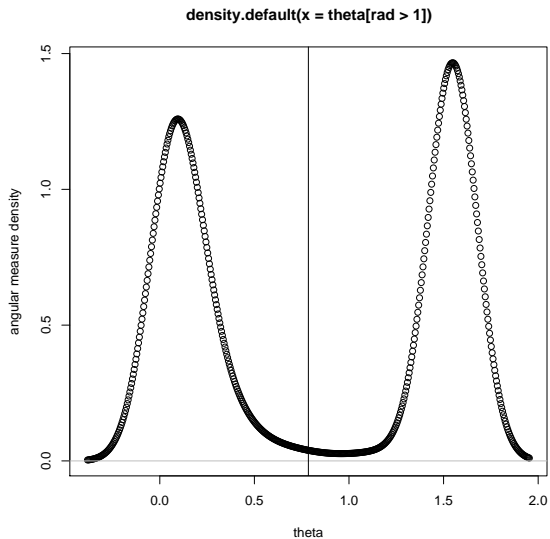


Figure 1: $k=1500$, Angular measure F,R; length=54343

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9. Hidden Regular Variation.

9.1. Why asymptotic independence creates problems.

- Estimators of various parameters may behave badly under asymptotic independence; eg, estimator of the spectral measure S . Estimators may be asymptotically normal with an asymptotic variance of 0 (oops!).
- Estimators of probabilities given by asymptotic theory may be uninformative.

Scenario: Estimate the probability of simultaneous non-compliance.

Suppose $\mathbf{Z} = (Z^{(1)}, Z^{(2)})$ = concentrations of different pollutants. Environmental agencies set critical levels $\mathbf{t}_0 = (t_0^{(1)}, t_0^{(2)})$ which not be exceeded. Imagine simultaneous *non-compliance* creates a health hazard. Worry about

$$[\text{health hazard}] = [\mathbf{Z} > \mathbf{t}_0] = [Z^{(j)} > t_0^{(j)}; j = 1, 2].$$

Asymptotic independence might lead one to report

$$P[\text{health hazard}] = P[\mathbf{Z} > \mathbf{t}_0] = 0.$$

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9.2. A submodel of asymptotic independence.

The random vector \mathbf{Z} has a distribution possessing *hidden regular variation* if

1. Regular variation on the big cone $\mathbb{E} = [0, \infty]^2 \setminus \{\mathbf{0}\}$:

$$t\mathbb{P}\left[\frac{\mathbf{Z}}{b(t)} \in \cdot\right] \xrightarrow{v} \nu,$$

(if \mathbf{Z} is standard, $b(t) \sim t$)

AND

2. Regular variation on the small cone $\mathbb{E}_0 = (0, \infty]^2$: \exists a non-decreasing function $b^0(t) \uparrow \infty$ such that

$$b(t)/b^0(t) \rightarrow \infty$$

and \exists a measure $\nu^0 \neq 0$ which is Radon on $\mathbb{E}_0 = (0, \infty]^2$ and such that

$$t\mathbb{P}\left[\frac{\mathbf{Z}}{b^0(t)} \in \cdot\right] \xrightarrow{v} \nu^0 = \text{hidden measure}$$

on the cone \mathbb{E}_0 .

Then there exists $\alpha^0 \geq \alpha$ such that $b^0 \in RV_{1/\alpha^0}$.

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Consequences:

- With the right formulation,

Second order regular variation + asy indep

⇒ hidden regular variation

⇒ asymptotic independence.

- **Reduction to one-dimensional regular variation:** Hidden regular variation means for every $\mathbf{s} \geq \mathbf{0}$, $\mathbf{s} \neq \mathbf{0}$, $\bigvee_{i=1}^d s^{(i)} Z^{(i)}$ has distribution with a regularly varying tail of index α and for every $\mathbf{a} \geq \mathbf{0}$, $\mathbf{a} \neq \mathbf{0}$, $\bigwedge_{i=1}^d a^{(i)} Z^{(i)}$ has a regularly varying distribution tail of index α^0 .

- In particular, hidden regular variation means both $Z^{(1)} \vee Z^{(2)}$ and $Z^{(1)} \wedge Z^{(2)}$ have regularly varying tail probabilities with indices α and α^0 . Note

$$\eta = 1/\alpha^0 = \text{coefficient of tail dependence}$$

(Ledford and Tawn (1996,1997)).

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- Define on $\mathcal{N} \cap \mathbb{E}_0$

$$S^0(\Lambda) = \nu^0\{\mathbf{x} \in \mathbb{E}^0 : |\mathbf{x}| \geq 1, \frac{\mathbf{x}}{|\mathbf{x}|} \in \Lambda\}$$

called the *hidden angular measure*.

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Sub-model (cont)–Examples:

Example 1: $d = 2$; independent random quantities $B, \mathbf{Y}, \mathbf{U}$ with

$$P[B = 0] = P[B = 1] = 1/2$$

and $\mathbf{Y} = (Y^{(1)}, Y^{(1)})$ is iid with

$$P[Y^{(1)} > x] = x^{-1}, \quad x > 1$$

and

$$b(t) = t.$$

Let \mathbf{U} have multivariate regularly varying distribution on \mathbb{R}^d and no asymptotic independence and $\exists \alpha^0 > 1, b^0(t) \in RV_{1/\alpha^0}, \nu^0 \neq 0,$

$$tP\left[\frac{\mathbf{U}}{b^0(t)} \in \cdot\right] \rightarrow \nu^0 \neq 0.$$

Define

$$\mathbf{Z} = B\mathbf{Y} + (1 - B)\mathbf{U}$$

which has hidden regular variation, and the property

$$S^0(N^0) := \nu^0\{\mathbf{x} \in \mathbb{E}_0 : \|\mathbf{x}\| > 1\} < \infty.$$

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Example 2: For $d = 2$, define $\mathbf{Z} = (Z^{(1)}, Z^{(2)})$ iid and Pareto distributed with

$$P[Z^{(i)} > x] = x^{-1}, \quad x > 1, \quad i = 1, 2.$$

Set

$$b(t) = t, \quad b^0(t) = \sqrt{t},$$

so that $b(t)/b^0(t) \rightarrow \infty$. Then \mathbf{Z} is asymptotically independent and possesses hidden regular variation with

$$\nu^0([\mathbf{x}, \infty]) = (x^{(1)}x^{(2)})^{-1}.$$

On \mathbb{E}

$$tP\left[\frac{\mathbf{Z}}{b(t)} \in \cdot\right] \xrightarrow{v} \nu,$$

$\nu(\mathbb{E}_0) = 0$, and on \mathbb{E}_0

$$tP\left[\frac{\mathbf{Z}}{b^0(t)} \in \cdot\right] \xrightarrow{v} \nu^0,$$

and

$$S^0(\mathbb{N}^0) := \nu^0\{\mathbf{x} \in \mathbb{E}_0 : \|\mathbf{x}\| > 1\} = \infty.$$

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HRV follows from

$$\begin{aligned} tP[Z^{(1)} > \sqrt{tx}, Z^{(2)} > \sqrt{ty}] \\ &= \sqrt{t}P[Z^{(1)} > \sqrt{tx}] \sqrt{t}P[Z^{(2)} > \sqrt{ty}] \\ &\rightarrow \frac{1}{xy}. \end{aligned}$$

Example 3: Let

$$\mathbf{Z} = \left(\frac{1}{U}, \frac{1}{1-U} \right).$$

where $U \sim U(0, 1)$. Then

$$\frac{1}{U} \wedge \frac{1}{1-U} \leq 2,$$

so $\frac{1}{U} \wedge \frac{1}{1-U}$ is not regularly varying.

Conclusions from Example 3:

- \mathbf{Z} possess asymptotic independence.
- \mathbf{Z} does not possess hidden regular variation.
- Testing for asymptotic independence by testing the minimum of the components does not work here. Testing using the min of the components is a test for HRV, not asy indep.

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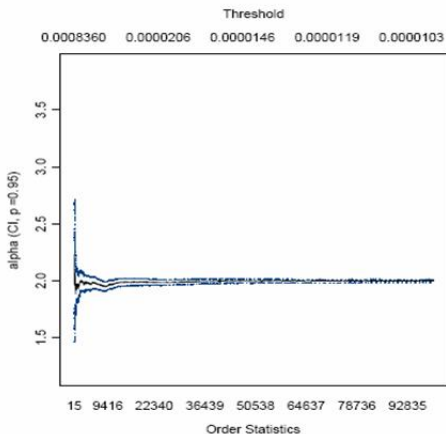
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9.3. Can We Detect Hidden Regular Variation?

Example 1: Simulation.

5000 pairs of iid Pareto, $\alpha = 1$; $\alpha^0 = 2$. Hillplot for rank transformed data taking minima of components.



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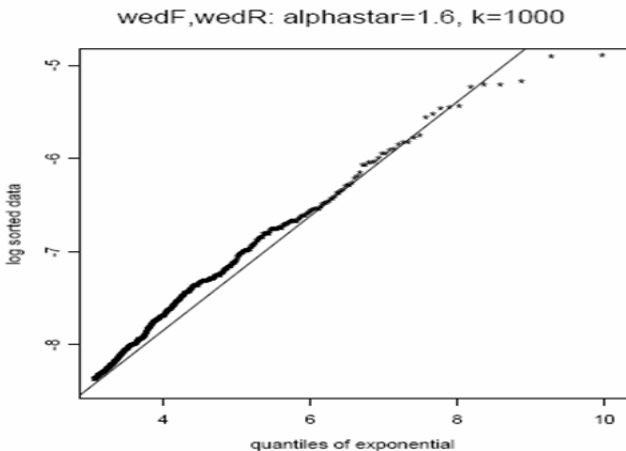
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Example 2: UNC Wed (F,R).

QQ plot of rank transformed data using 1000 upper order statistics for UNC Wed (F,R); $\alpha = 1$ and $\hat{\alpha}^0 = 1.6$.



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9.4. Estimating ν^0 .

The hidden measure ν^0 has a spectral measure S^0 defined on \mathbb{N}^0 , the unit sphere in \mathbb{E}_0 :

$$S^0(\Lambda) := \nu^0\{\mathbf{x} \in \mathbb{E}_0 : \|\mathbf{x}\| > 1, \frac{\mathbf{x}}{\|\mathbf{x}\|} \in \Lambda\}.$$

S^0 may not necessarily be finite.

We estimate S^0 rather than ν^0 .

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Estimation procedure (Heffernan and Resnick, 2007) for estimating ν^0 :

1. Replace the heavy tailed multivariate sample $\mathbf{Z}_1, \dots, \mathbf{Z}_n$ by the n vectors of reciprocals of anti-ranks $1/\mathbf{r}_1, \dots, 1/\mathbf{r}_n$, where

$$r_i^{(j)} = \sum_{l=1}^n 1_{[Z_l^{(j)} \geq Z_i^{(j)}]}; \quad j = 1, \dots, d; \quad i = 1, \dots, n.$$

2. Compute normalizing factors (min across components)

$$m_i = \bigwedge_{j=1}^d \frac{1}{r_i^{(j)}}, \quad i = 1, \dots, n,$$

and their order statistics

$$m_{(1)} \geq \dots \geq m_{(n)}.$$

3. Compute the polar coordinates $\{(R_i, \Theta_i); i = 1, \dots, n\}$ of

$$\{(1/r_i^{(j)}; j = 1, \dots, d); i = 1, \dots, n\}.$$

4. Estimate S^0 using the Θ_i corresponding to $R_i \geq m_{(k)}$.

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Details:

- If ν^0 is infinite, let $\aleph_0(K)$ be compact subset of \aleph_0 .
 - For $d = 2$ where \aleph can be parameterized as $\aleph = [0, \pi/2]$ and $\aleph_0 = (0, \pi/2)$, set $\aleph_0(K) = [\delta, \pi/2 - \delta]$ for some small $\delta > 0$.
- Then as $n \rightarrow \infty$ and $k = k(n) \rightarrow \infty$, and $k/n \rightarrow 0$,

$$\frac{\sum_{i=1}^n 1_{[R_i \geq m(k), \Theta_i \in \aleph_0(K)]} \epsilon_{\Theta_i}}{\sum_{i=1}^n 1_{[R_i \geq m(k), \Theta_i \in \aleph_0(K)]}} \Rightarrow S_0\left(\cdot \bigcap \aleph_0(K)\right).$$

- If ν^0 is finite, we can replace $\aleph_0(K)$ with \aleph_0 . (But how would we know we can do this?)

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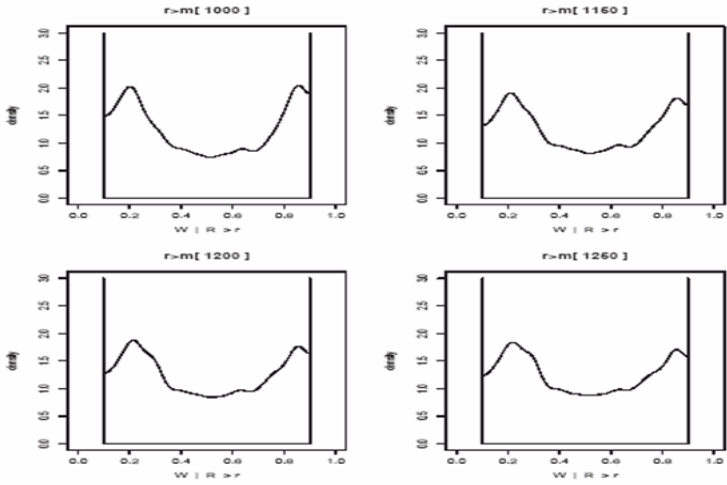
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Example.

UNC (F,R), April 26. Asymptotic independence present. Since S^0 may be infinite, we restricted estimation to the angular interval interval $[0.1,0.9]$ instead of all of $[0, 1]$. All plots show the hidden measure to be bimodal with peaks around 0.2 and 0.85.



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10. Conditional models.

Heffernan & Tawn models (Heffernan and Tawn, 2004):

$$P\left[\frac{X - \beta(t)}{\alpha(t)} \leq x | Y = t\right] \rightarrow G(x), \quad t \rightarrow \infty. \quad (9)$$

Alternate approaches to asymptotic independence consider

$$P[X \leq x | Y > t] \rightarrow G(x), \quad t \rightarrow \infty,$$

which comes from

$$tP\left[\left(X, \frac{Y}{t}\right) \in \cdot\right] \rightarrow H \times \nu_1$$

where H is a pm, $\nu_1(x, \infty] = x^{-1}$, $x > 1$. See Maulik et al. (2002).

With Jan Heffernan, meld 2 approaches (Heffernan and Resnick, 2007) and reformulate as

$$tP\left[\left(\frac{X - \beta(t)}{\alpha(t)}, \frac{Y - b(t)}{a(t)}\right) \in \cdot\right] \xrightarrow{v} \mu$$

where μ satisfies non-degeneracy assumptions. This relates to regular variation on the cone \mathbb{E}_\square .

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10.1. Basic Convergence

Given a random vector (X, Y) with

$$F_Y(x) := P[Y \leq x] \in MDA(G_\gamma),$$

and $\exists b(\cdot) \in \mathbb{R}, a(\cdot) > 0$ such that for some $\gamma \in \mathbb{R}$, as $t \rightarrow \infty$,

$$\left(P \left[\frac{Y - b(t)}{a(t)} \leq x \right] \right)^t \rightarrow G_\gamma(x) = \exp\{-(1 + \gamma x)^{-1/\gamma}\}, \quad t \rightarrow \infty.$$

Further assume $\exists \beta(\cdot) \in \mathbb{R}, \alpha(\cdot) > 0$ and a Radon measure μ such that

$$tP \left[\left(\frac{X - \beta(t)}{\alpha(t)}, \frac{Y - b(t)}{a(t)} \right) \in \cdot \right] \xrightarrow{v} \mu(\cdot), \quad (10)$$

in $M_+([-\infty, \infty] \times (-\infty, \infty])$, and where μ is non-null and satisfies **non-degeneracy conditions**: for each fixed $y \in \{x : (1 + \gamma x)^{-1/\gamma} > 0\}$,

1. $\mu((-\infty, x] \times (y, \infty])$ is not a degenerate distribution function in x ;
2. $\mu((-\infty, x] \times (y, \infty]) < \infty$.

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10.2. Observations:

- The **Basic Convergence** (10) implies the conditioned limit

$$P\left[\frac{X - \beta(t)}{\alpha(t)} \leq x \mid Y > b(t)\right] \rightarrow \mu([-\infty, x] \times (0, \infty]),$$

where the limit is assumed to be a proper probability distribution in x .

- WLOG can assume Y is heavy tailed and reduce the basic convergence to a more **standard form**:

$$tP\left[\left(\frac{X - \beta(t)}{\alpha(t)}, \frac{Y^*}{t}\right) \in \cdot\right] \xrightarrow{v} \mu^*(\cdot) \quad (11)$$

in $M_+([-\infty, \infty] \times (0, \infty])$ (μ^* is modified from μ). For instance,

$$Y^* = b^\leftarrow(Y) \quad \text{and} \quad b(t) = \left(\frac{1}{1 - F_Y}\right)^\leftarrow(t).$$

- Suppose (X, Y^*) are regularly varying on $[0, \infty]^2 \setminus \{\mathbf{0}\}$.
 - With no asymptotic independence in the EVT sense, **Basic Convergence** automatically holds.
 - With asymptotic independence in EVT sense, **Basic Convergence** is an extra assumption.

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10.3. Other Consequences.

- A convergence to types argument implies variation properties of $\alpha(\cdot)$ and $\beta(\cdot)$: Suppose (X, Y^*) satisfy the condition (11). \exists two functions $\psi_1(\cdot), \psi_2(\cdot)$, such that for all $c > 0$,

$$\lim_{t \rightarrow \infty} \frac{\alpha(tc)}{\alpha(t)} = \psi_1(c), \quad \lim_{t \rightarrow \infty} \frac{\beta(tc) - \beta(t)}{\alpha(t)} \rightarrow \psi_2(c). \quad (12)$$

locally uniformly.

- This means

$$\alpha(\cdot) \in RV_\rho, \quad \rho \in \mathbb{R} \quad \text{and} \quad \psi_1(c) = c^\rho, \quad c > 0.$$

- \exists important cases where $\psi_2 \equiv 0$ (bivariate normal). However, if $\psi_2 \not\equiv 0$, then ((Geluk and de Haan, 1987, page 16), Bingham et al. (1987))

$$\psi_2(x) = \begin{cases} k \frac{(x^\rho - 1)}{\rho}, & \text{if } \rho \neq 0, x > 0, \\ k \log x, & \text{if } \rho = 0, x > 0, \end{cases} \quad (13)$$

for $k \neq 0$.

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10.4. When can both components in the basic convergence be standardized?

- Can sometimes also standardize the X variable so that

$$\begin{aligned}
 tP\left[\frac{\beta^{\leftarrow}(X)}{t} \leq x, \frac{Y^*}{t} > y\right] &= tP\left[\frac{X^*}{t} \leq x, \frac{Y^*}{t} > y\right] \\
 &\rightarrow \mu^*([-\infty, \psi_2(x)] \times (y, \infty]) \\
 &= \mu^{**}([-\infty, x] \times (y, \infty]) \quad (t \rightarrow \infty). \quad (14)
 \end{aligned}$$

When?? Short version: When and only when μ^* (or μ) is not a product measure (Das and Resnick, 2008).

- When is μ^* a product measure?

Answer: $\mu^* = H \times \nu_1$ iff $\psi_1 \equiv 1$ ($\alpha(\cdot)$ is sv) and $\psi_2 \equiv 0$.

- If you can standardize, how do you do it?

- * One answer: If $\beta(t) \geq 0$ and β^{\leftarrow} is non-decreasing on the range of X , then (14) is possible (provided μ is NOT a product).
- * If the condition $\beta(t) \geq 0$ and β^{\leftarrow} is non-decreasing fails, then a transformation of X allows one to reduce the problem to the previous case.

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- If we have $X \geq 0$ and both regular variation on $[0, \infty]^2 \setminus \{0\}$

$$tP\left[\left(\frac{X}{a'(t)}, \frac{Y^*}{t}\right) \in \cdot\right] \xrightarrow{v} \nu_*(\cdot)$$

and (14):

$$tP\left[\frac{\beta^{\leftarrow}(X)}{t} \leq x, \frac{Y^*}{t} > y\right] \rightarrow \mu^*([-\infty, \psi_2(x)] \times (y, \infty])$$

on $[0, \infty] \times (0, \infty]$, then we have a form of **hidden regular variation** since

$$[0, \infty] \times (0, \infty] \subset [0, \infty]^2 \setminus \{0\}.$$

More on this in a bit.

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10.5. Form of the limit.

10.6. Case 1. Assume μ is not a product.

Then can standardize X and for the case that $\beta(t) \geq 0$ and $\beta(t) \uparrow$

$$tP\left[\frac{\beta^{\leftarrow}(X)}{t} \leq x, \frac{Y^*}{t} > y\right] = tP\left[\frac{X^*}{t} \leq x, \frac{Y^*}{t} > y\right]$$

$$\rightarrow \mu^*([0, \psi_2(x)] \times (y, \infty]) = \mu^{**}([0, x] \times (y, \infty]), \quad (t \rightarrow \infty)$$

on $[0, \infty] \times (0, \infty]$. This is standard regular variation on the cone $[0, \infty] \times (0, \infty]$ so

$$\mu^{**}(c\Lambda) = c^{-1}\mu^{**}(\Lambda).$$

\exists angular measure: Let

$$\|(x, y)\| = x + y, \quad \aleph = \{(w, 1 - w) : 0 \leq w < 1\}$$

and

$$\mu^{**}\left\{\mathbf{x} : \|\mathbf{x}\| > r, \frac{\mathbf{x}}{\|\mathbf{x}\|} \in A\right\} = r^{-1}S(A),$$

where S is a measure on \aleph or $[0, 1)$.

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Warning:

S does not have to be finite

but to guarantee

$$P\left[\frac{X^*}{t} \leq x | Y^* > t\right] \rightarrow H^{**}(x) = \mu^{**}([0, x] \times (1, \infty))$$

is proper pm, need

$$\int_{[0,1)} (1-w)S(dw) = 1. \quad (15)$$

Conclusions for Case 1:

- Can write $\mu^{**}([0, x] \times (y, \infty])$ as function of S and get characterization of the class of limit measures.
- Hence, limit measures μ^{**} are in 1-1 correspondence with class of measures on $[0, 1)$ satisfying (15).
- Alternatively, a scaling argument gives class of μ^{**} with following description:

$$\mu^{**}([0, x] \times (y, \infty]) = y^{-1}H^{**}\left(\frac{x}{y}\right), \quad (x, y) \in [0, \infty] \times (0, \infty]$$

for any proper prob distribution H^{**} .

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10.7. Case 2: Assume μ is a product.

Any measure of the form

$$\mu^{**}([0, x] \times (y, \infty)) = y^{-1}H^{**}(x),$$

for a prob distribution H^{**} is a possible limit.

End of story for Case 2.

10.8. Random norming and change of coordinates.

Suppose μ is not a product. Then both variables X, Y can be standardized

$$(X, Y) \mapsto (X^*, Y^*)$$

and taking the ratio X^*/Y^* gives a product form limit. After transforming

$$(X^*, Y^*) \mapsto \left(\frac{X^*}{Y^*}, Y^* \right)$$

we get

$$tP \left[\left(\frac{X^*}{Y^*}, \frac{Y^*}{t} \right) \in \cdot \right] \rightarrow G \times \nu_1(\cdot)$$

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in $M_+([0, \infty] \times (0, \infty])$ where

$$\nu_1(y, \infty] = y^{-1}, \quad G(x) = \int_{[0, \frac{x}{1+x}]} (1-w)S(dw).$$

(Heffernan and Resnick, 2007, Maulik et al., 2002).

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The condition

$$tP\left[\left(\frac{X^*}{Y^*}, \frac{Y^*}{t}\right) \in \cdot\right] \rightarrow G \times \nu_1(\cdot) \quad (16)$$

can be detected by reduction to one dimensional regular variation: We have (16) iff

$$Y^* 1_{[X^*/Y^* \in \Lambda]}$$

has standard regularly varying distribution for any $\Lambda \in \mathcal{B}(\mathbb{R}_+)$, or iff

$$aX^* \wedge Y^*$$

has a standard regularly varying distribution for any $a > 0$. (Das and Resnick, 2008)

Statistical implications?? (Das & Resnick, 2008.)

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10.9. The cone $\mathbb{E}_\square = [0, \infty) \times (0, \infty)$ and conditioned limit laws.

10.9.1. Limit measure is a product.

- Suppose (X^*, Y^*) is standard regularly varying on the cone \mathbb{E}_\square , such that

$$t\mathbb{P}\left[\left(\frac{X^*}{t}, \frac{Y^*}{t}\right) \in \cdot\right] \xrightarrow{v} \mu^{**}(\cdot) \quad \text{in } M_+(\mathbb{E}_\square) \quad (17)$$

for some Radon measure $\mu^{**}(\cdot)$ on \mathbb{E}_\square satisfying the non-degeneracy conditions. Then $\mu^{**}(\cdot)$ cannot be a product measure.

- Suppose we have

$$t\mathbb{P}\left[\left(\frac{X - \beta(t)}{\alpha(t)}, \frac{Y^*}{t}\right) \in \cdot\right] \xrightarrow{v} G \times \nu_1(\cdot) \text{ in } M_+([-\infty, \infty) \times (0, \infty)). \quad (18)$$

Then we cannot have a monotone standardization function $f(\cdot)$ such that

$$t\mathbb{P}\left[\left(\frac{f(X)}{t}, \frac{Y^*}{t}\right) \in \cdot\right] \xrightarrow{v} \mu(\cdot) \quad \text{in } M_+(\mathbb{E}_\square). \quad (19)$$

No standardization is possible. (Das and Resnick, 2008).

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10.9.2. Limit measure is not a product.

Given the basic convergence,

$$tP \left[\left(\frac{X - \beta(t)}{\alpha(t)}, \frac{Y - b(t)}{a(t)} \right) \in \cdot \right] \xrightarrow{v} \mu(\cdot), \quad (20)$$

where μ is NOT a product measure, can always standardize so that

$$P \left[\left(\frac{X^*}{t}, \frac{Y^*}{t} \right) \in \cdot \right] \xrightarrow{v} \mu^{**}(\cdot), \quad \text{in } M_+(\mathbb{E}_{\Gamma}). \quad (21)$$

And vice versa. Given (21), \exists monotone transformations f_1, f_2 such that

$$(X, Y) = (f_1(X^*), f_2(Y^*))$$

satisfies (20).

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11. Consistency

- In practice, should one condition on X or Y ?
- What if one could do either?

Then the distribution is in the domain of attraction of an EV distribution.

Theorem. Suppose we have a bivariate random vector $(X, Y) \in \mathbb{R}^2$ and functions $\alpha(\cdot), a(\cdot), \chi(\cdot), c(\cdot) > 0$ and $\beta(\cdot), b(\cdot), \phi(\cdot), d(\cdot) \in \mathbb{R}$ such that

$$t\mathbb{P}\left[\left(\frac{X - \beta(t)}{\alpha(t)}, \frac{Y - b(t)}{a(t)}\right) \in \cdot\right] \xrightarrow{v} \mu(\cdot) \text{ in } M_+([-\infty, \infty] \times (-\frac{1}{\gamma}, \infty]), \quad (22)$$

$$t\mathbb{P}\left[\left(\frac{X - \phi(t)}{\chi(t)}, \frac{Y - d(t)}{c(t)}\right) \in \cdot\right] \xrightarrow{v} \nu(\cdot) \text{ in } M_+((-\frac{1}{\lambda}, \infty] \times [-\infty, \infty]) \quad (23)$$

for some $\lambda, \gamma \in \mathbb{R}$.

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Then (X, Y) is in the domain of attraction of a multivariate extreme value distribution on

$$\mathbb{E}_{\lambda, \gamma} := \left[-\frac{1}{\lambda}, \infty\right] \times \left[-\frac{1}{\gamma}, \infty\right] \setminus \left\{\left(-\frac{1}{\gamma}, -\frac{1}{\lambda}\right)\right\},$$

that is,

$$t\mathbb{P}\left[\left(\frac{X - \beta(t)}{\alpha(t)}, \frac{Y - b(t)}{a(t)}\right) \in \cdot\right] \xrightarrow{v} (\mu \diamond \nu)(\cdot) \text{ in } M_+(\mathbb{E}_{\lambda, \gamma})$$

where $(\mu \diamond \nu)(\cdot)$ is a Radon measure on $M_+(\mathbb{E}_{\lambda, \gamma})$.

Conclusion: So the conditioned limit theory is only different than classical EVT if we assume we can condition only on one variable but not on the other.

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Final thoughts

- How practical is all this?
- When should you try to use this theory rather than EVT?
- Can this theory be used to supplement EVT in the presence of asymptotic independence? This seems the most likely road to applicability.
- How do we do estimation and inference?

We are thinking about all this.

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